

Getting Started with Evaluation Board EVB002

The GreenArrays EVB002 Evaluation Board is a versatile and powerful application development platform for the GA144-1.20 chips. As such it has many configuration options. The current Printed Circuit Board (PCB) revision shown on the silkscreen is 0h. It is currently shipped with configuration settings as shown herein, and with polyFORTH® that may be booted from flash.

Please familiarize yourself with this information before connecting anything to your new board. It will walk you through initial connection, check-out and use of the board.

In addition, please download and read the other relevant documentation such as the Programmers' Reference for the F18 computers (DB001), the G144A12 Chip Data Book (DB002), the Evaluation Board Data Book (DB014), and the Programmers' References for arrayForth® version 3, polyFORTH, and other software as appropriate. The current editions of all GreenArrays documents, including this one, may be found on our website at <http://www.greenarraychips.com>. It is always advisable to ensure that you are using the latest documents before starting work.

Your satisfaction is very important to us! Please contact Hotline@greenarraychips.com if you have questions or need help with using your board.

Please see DB014 for a description of the differences between EVB001 and EVB002 kits.

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1. Initial Check-Out

This section outlines procedures for inspecting a board and verifying its configuration and function. These procedures are very similar to those we follow in the factory before shipping boards to you.

1.1 Recommended Working Area

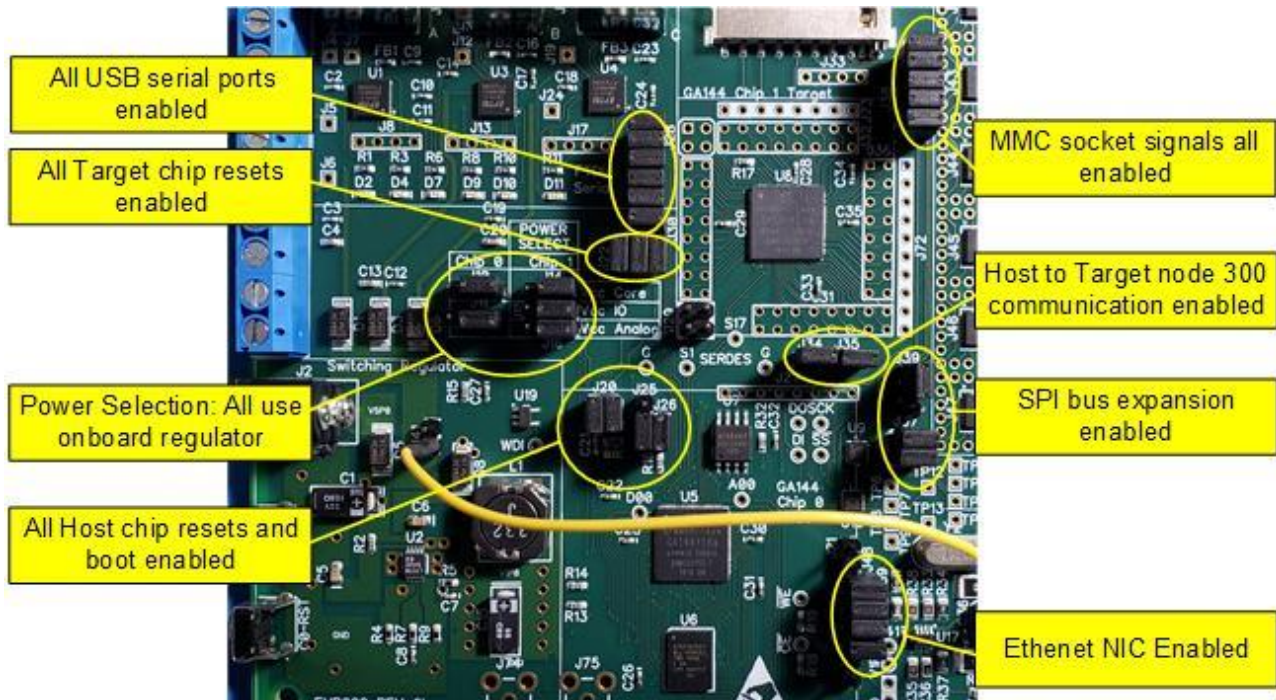
Since the purpose of this board is to provide you with direct access to the very sensitive pins of your chips, you should set up a working area to protect the chips against Electrostatic Discharge (ESD) from your body. We recommend, as a basic precaution, that you use an anti-static mat connected to a single-point earth ground in common with any other equipment in use, and that you wear a wrist strap, as shown in the adjacent photo, while handling or probing the board. It is always a good idea to avoid wearing clothing that tends to accumulate static charges, and to touch the mat or a grounded part of the board when approaching the work area and before touching other parts of the board. *Note that the metal shield of the SD card slot is a good ground for this purpose; the shields of the USB connectors are not grounded.*



If you have any questions about correct procedures, please check our website or contact the hotline for more information

1.2 Factory Default Jumper Settings

Begin by setting all jumpers to the default settings as we shipped the board to you. Please refer to this illustration and to the detailed information that follows:



1.2.1 Table of Jumpers

Host and Target Power Select

J10

1	External Host Pwr
2	V _{DD} C to Host
3	

J11

1	External Host Pwr
2	V _{DD} l and A to Host
3	Main 1.8v Bus

J14

1	External Target Pwr
2	V _{DD} C to Target
3	Main 1.8v Bus

J15

1	External Target Pwr
2	V _{DD} l to Target
3	Main 1.8v Bus

J16

1	External Target Pwr
2	V _{DD} A to Target
3	Main 1.8v Bus

Host-Target Communication

J34

1	Host 300.1
2	Target 300.1

J35

1	Host 300.17
2	Target 300.17

USB Port Data Connections to Chips

J23

From Port A	1	2	Host 708.17
To Port A	3	4	Host 708.1
From Port B	5	6	Host 200.17
To Port B	7	8	Host 100.17
From Port C	9	10	Target 708.17
To Port C	11	12	Target 708.1

Target Chip Reset

J22

Host 500.17	1	2	Target RESET-pin
USB C RTS signal	3	4	
Target reset circuit	5	6	

Host Chip Reset and Boot

J20

RESET pin	1	2	RESET pin
USB A RTS	3	4	J25.2

J25

1	RST- from reset/dog chip
2	Signal to J20.4
3	Reset Button & RC Circuit

J26

1	Host 705.17
2	NO BOOT when IN

SD/MMC Socket Signals

Socket pins	J38	J40	SPI bus signals
CLK/SCLK	1	1	SPI CLK MMC
DAT3/CS-	2	2	SPI CS- MMC
CMD/SI	3	3	SPI DO
DAT0/SO	4	4	SPI DI
V _{DD}	5	5	1.8v

SPI Bus Expansion

J39

1	Host 600.17
2	FLASHENABLE-
3	Ground

J37

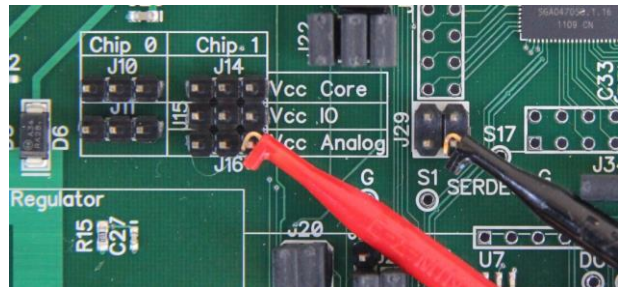
FLASH ENABLE- on SPI bus.	1	2	Inputs to NAND. Output low enables MMC on SPI bus.
	3	4	

Ethernet NIC Signals

Host pins	J21	J48	NIC Signals
617.ao	1		
617.ai	2		
517.17	3	1	Y2 xtal hi
417.17	4	2	Y2 xtal hi
317.17	5	3	Tx (to opamp)
217.17	6	4	Rx (raw)
117.ao	7		
117.ai	8		

1.3 Check the Power Supply

In the factory, we check the power supply before applying DC power to most of the board. Begin by removing all of the power select jumpers J10, J11, J14, J15 and J16 as shown here. Connect a voltmeter as shown; all four pins of header J29, near the Target chip, are ground and pin 3 (right side) of any of the power select headers is connected to the output of the on-board switching regulator.



After setting the board up in this way, provide input power to the regulator, using either a "wall-wart" in J2, or any of the three USB connections J3, J9 or J18. Your voltmeter should indicate very nearly 1.8 volts. We do not recommend checking resistance between V_{DD} and ground on this board, because many meters apply high voltages exceeding some chips' limits. When the checks are complete, re-insert the power select jumpers.

If you use a "wall-wart" power source, it needs to provide 3.6 to 19.5V (5.0V if you will use J41 to power the Ethernet interface) on a type "N" connector, positive voltage on center pin. If the supply can produce 4.5 to 5 watts then it should be able to power the 80% efficient switching regulator at its maximum rated output of 2A at 1.8v.

1.4 Identify and Set-up COM Ports for USB A, B, C

Each USB connector identified as A, B, and C reading left to right goes to an FTDI USB to serial adaptor chip. These have unique serial numbers for the benefit of systems that use them to assign a permanent COM port number to each device. If using Windows or Parallels, attach the cables one at a time, identify the COM port numbers assigned using Device Manager, and find Advanced Port Settings. Change Latency Timer from default 16 ms to 1 ms, and change USB Transfer Sizes from default 4096 to 128 bytes. These settings will greatly improve performance. Subsequently each port may be used at any baud rate from 19,200 to 921,600. Turn off *Serial Enumerator*; turn on *Set RTS On Close* and *Disable Modem Ctrl At Startup*. See the arrayForth-3 User's Manual installation sections for more information and for other platforms. You must keep track of which COM port numbers connect to which of the board's USB ports.

1.5 Simple Confidence Test using polyForth

Connect any serial terminal emulator program such as PuTTY or HyperTerm to USB port B, 8 data bits, no parity, one stop bit *and no flow control*. Remove NO-BOOT jumper J26 and press the host chip reset button (CO-RST) on the lower left corner of the board, then hit the space bar on the terminal to auto-baud polyForth. You should see:

```
pF/G144.03b1 12/21/18 (or whichever version is in flash)
hi _
```

Hit the enter key. You should see another `ok` which indicates that a great deal of the board is working. *Please contact us right away if you do not see these things!*

1.6 Test GA144 Chips using arrayForth 3

To completely self-test the chips, download DB013 *arrayForth 3 User's Manual* and the current aF3 Windows Installer from our website (see 3.2 below). Follow instructions in the User's Manual for your host platform to install the arrayForth-3 software and identify and configure your COM ports. You do not need to edit the arrayForth code at this point but you do need to get the COM ports identified and the connections to USB ports A and C configured as instructed for your platform.

With USB ports A and C connected to the EVB002, and with NO-BOOT jumper J26 installed, run saneForth on your PC or other platform as per instructions for your platform. Type the following phrases to run self-tests, substituting the actual COM port for USB A (host IDE) for 10 and the port for USB C (target IDE) for 12:

```
10 SELFTEST (runs factory tests on host chip)
12 SELFTEST (runs factory tests on target chip)
10 AUTOTEST (tests target chip under host chip control using synchronous boot,
and tests SERDES between the chips)
```

Hit ENTER at the end of each of the above phrases. While a test is running you will see a screen like the one shown here. The "Test Progress" is initially **busy** in white on blue, and while the test is running the numbers on the third line are updated as the testing progresses. When the testing is completed successfully, you will see the "Ok!" advisory in black on green. If there is a failure, it will instead display "FAIL!" in black on magenta.

```
arrayForth 3 G144A12
Test Progress: Ok!
Ph -ID- -TGT- Pos xANS- xRVAL NRUNS VVALU
3 2013 701 7 0 0 11520 1
ok
```

Please contact us right away if you do not see the expected results or if you have any difficulty in running these tests!

2. Move On to Programming

Now that you've verified the integrity of your board and its connections with a host machine, it's time to take a closer look at the two main development tools used in programming our chips.

- **arrayForth-3 (aF-3)** is a full blown, self-reproducing professional operating system suite for IA32 PC platforms (saneFORTH) and for the GA144 running in a Virtual Machine of several nodes (polyFORTH). Many of our software development tools run in both environments, although some (like Softsim) are only practical on the PC while others (like the internal IDE) are only feasible running inside the chip itself. Mass storage is provided by the PC (serial disk) and by the EVB002 (16 MB SPI Flash). All software supported by Greenarrays has been developed and is maintained using aF-3.

aF-3 runs on both saneForth (PC platform) and polyForth (on the EVB002). Some of the tools are only implemented on one of the platforms, by intention. Two tools, "softsim" and the external IDE based flash burner, are not yet supported by aF-3.

- **eForth** is a very simple and portable implementation of ANS Forth. This particular implementation runs on a 16-bit Virtual Machine that runs on our chips. eForth requires only a terminal emulator on USB port B, although the supplied emulator provides additional useful capabilities. It's not supported by GreenArrays but source code is available and it may be supported by individuals.
- **Third Party Tools** have been developed by at least two users of our chips. See our website, Documentation & Software, for more information about these tools.

Please see our website for to download these tools, their documentation, and other relevant code, documentation and application notes.

3. Resources and Details

3.1 What's in the Box

In addition to the Eval Board itself, there is an antistatic bag containing parts you may find useful. The exact composition of this bag is subject to change, but as of the time of this writing it contains the following items: One Dual voltage, 1 or 2 GB MMC card intended for use as primary mass storage by polyFORTH when MMC is supported. One USB cable. Two Clip-leads. One long jumper wire for Ethernet transmitter power. One each DB9, VGA, and USB-B sockets. Three TRS audio jacks. Long single and double row male headers that may be cut up and soldered where needed. Five LEDs and five 47 Ω resistors for diagnostic and general use.

3.2 Getting Help

There is a special webpage for customers who have bought our evaluation boards; please visit it now at this URL: <http://www.greenarraychips.com/home/support> This page is updated frequently and will always have the latest information for you. Email hotline@greenarraychips.com for prompt replies to your questions. The hotline team will provide you with additional contact information for direct, personal support such as Skype ID and phone numbers upon request.

General documentation and downloads are posted in <http://www.greenarraychips.com/home/documents>

3.3 Errata in Current PCB Revision

PCB REV	DESCRIPTION	FIX OR WORK-AROUND

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